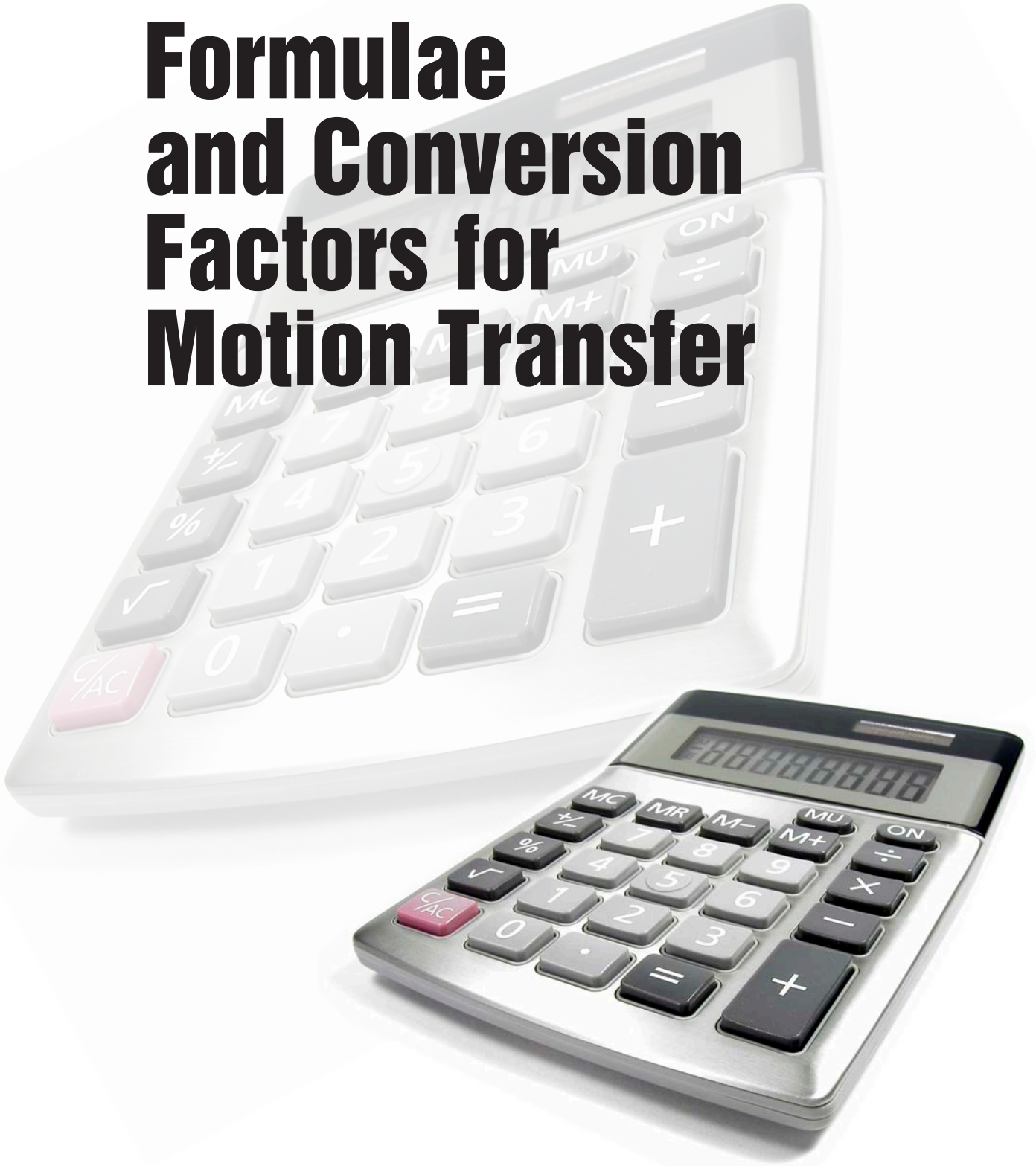




Formulae and Conversion Factors for Motion Transfer



Formulae and Conversion Factors

SI BASE UNITS

Quantity	Unit Symbol	Name
length	m	metre
mass	kg	kilogram
time	s	second
electric current	A	ampere
Thermodynamic temperature	K	kelvin
luminous intensity	cd	candela

LETTER SYMBOLS & SI UNITS IN POWER TRANSMISSION ENGINEERING

Symbol	Quantity	SI Unit Symbol	Name
Mechanics			
E	modulus of elasticity (Young's modulus)	Pa	pascal
F	force	N	Newton
G (W)	weight	N	Newton
J	moment of inertia	kgm ²	kilogram metre squared
M (T)	torque	Nm	Newton metre
m	mass	kg	kilogram
P	power	W	watt
p	pressure	Pa	pascal
ρ	density (mass density)	kg/m ³	-
σ	stress	Pa	pascal
W (E)	work (energy)	J	joule
η	efficiency	1	-
μ	coefficient of friction	1	-

FORMULAE

International System(SI)

Imperial System (FPS)

POWER

Lifting motion
$P = \frac{m \cdot g \cdot v}{\eta \cdot 1000}$
Linear motion
$P = \frac{F_r \cdot v}{1000}$
$F_r = \mu \cdot m \cdot g$
Rotary motion
$P = \frac{M \cdot n}{9550}$
P - Power in kW
F _r - Frictional resistance in N
m - Mass in kg
g - Acceleration of free fall (9.81) in m/s ²
v - Velocity in m/s
η - Efficiency in decimals
μ - Coefficient of friction
M - Torque in Nm
n - Rotational speed in 1/min or r/min

Lifting motion
$P = \frac{W \cdot v}{\eta \cdot 33000}$
Linear motion
$P = \frac{F_r \cdot v}{33000}$
$F_r = \mu \cdot W$
Rotary motion
$P = \frac{M \cdot n}{5250}$
P - Power in hp
F _r - Frictional resistance in lbf
W - Weight in lb
v - Velocity in ft/min
η - Efficiency in decimals
μ - Coefficient of friction
M - Torque in lbf . ft
n - Rotational speed in rpm

International System(SI)

Imperial System (FPS)

TORQUE

M - F . r
$P = \frac{9550 \cdot P}{n}$
M - Torque in Nm
F - Force in N
r - Radius of lever in m
P - Power in kW
n - Rotational speed in 1/min or r/min

M - F . r
$P = \frac{5250 \cdot P}{n}$
M - Torque in lbf . ft
F - Force in lbf
r - Radius of lever in ft
P - Power in hp
n - Rotational speed in rpm

WORK

W - F . s = m . g . s
$W = \frac{j \cdot n^2}{182.5}$
W - Work (energy) in Nm = Ws = J
F - Force in N
s - Length of path in m
m - Mass in kg
g - Acceleration of free fall (9.81) in m/s ²
J - Moment of inertia in kgm ²
n - Rotational speed in 1/min or r/min

W - F . s
$W = \frac{WK^2 \cdot n^2}{5880}$
W - Work (energy) in lb . ft
F - Force in lbf
s - Length of path in ft
m - Mass in kg
g - Acceleration of free fall (9.81) in m/s ²
WK ₂ - Flywheel effect lb . ft ²
n - Rotational speed in rpm

ACCELERATION OR BRAKING TIME

$t_a = \frac{j \cdot n}{9.55 M_a}$
t _a - Acceleration or braking time in s
J - Moment of inertia in kgm ²
n - Rotational speed in 1/min or r/min
M _a - Acceleration or braking torque in Nm

$t_a = \frac{WK^2 \cdot n}{308 M_a}$
t _a - Acceleration or braking time in s
WK ₂ - Flywheel effect in kgm ²
n - Rotational speed in rpm
M _a - Acceleration or braking torque in lb . ft

MOMENT OF INERTIA

Solid Cylinder
$J = \frac{1}{2} \cdot m \cdot r_{ext}^2$
$= \frac{1}{32} \cdot 1000 \cdot \pi \cdot \rho \cdot l \cdot d_{ext}^4$
$= 98 \rho \cdot l \cdot d_{ext}^4$
Hollow Cylinder
$J = \frac{1}{2} \cdot m \cdot (r_{ext}^2 + r_{int}^2)$
$= \frac{1}{32} \cdot 1000 \cdot \pi \cdot \rho \cdot l \cdot (d_{ext}^4 - d_{int}^4)$
$= 98 \cdot \rho \cdot l \cdot (d_{ext}^4 - d_{int}^4)$

Solid Cylinder
$WK_2 = \frac{1}{2} \cdot W \cdot r_{ext}^2$
$= \frac{\pi \cdot \rho \cdot l \cdot d_{ext}^4}{32}$
$= 0.1 \rho \cdot l \cdot d_{ext}^4$
Hollow Cylinder
$WK_2 = \frac{1}{2} \cdot W \cdot (r_{ext}^2 + r_{int}^2)$
$= \frac{\pi \cdot \rho \cdot l \cdot (d_{ext}^4 - d_{int}^4)}{32}$
$= 0.1 \cdot \rho \cdot l \cdot (d_{ext}^4 - d_{int}^4)$

torsional stiffness and resonant frequency

$$C_T \leq \left(\frac{FR \times 2 \pi}{J_M + J_L} \right)^2 \quad FR \leq \frac{1}{2 \pi} \times \sqrt{\left(\frac{1}{J_M} + \frac{1}{J_L} \right)} \times C_T$$

Where
C_T = torsional stiffness (Nm/rad);
J_M = motor inertia (kgm²)
FR = resonant frequency (Hz)
J_L = load inertia (kgm²)

Formulae and Conversion Factors

FORCE

		N	kp	p	tonf (UK)	lbf	ozf
1N	=	1	0.1020	102.0	100.4×10^{-6}	0.2248	3.597
1kp	=	9.807	1	1000	0.984×10^{-3}	2.205	35.27
1p	=	9.81×10^{-3}	1×10^{-3}	1	0.984×10^{-6}	2.2×10^{-3}	35.3×10^{-3}
1tonf (UK)	=	9964	1016	1.02×10^6	1	2240	35.8×10^3
1lbf	=	4.448	0.4536	453.6	0.5×10^{-6}	1	16
1ozf	=	-	28.4×10^{-3}	28.35	27.9×10^{-6}	62.5×10^{-3}	1

VELOCITY

		km/h	m/min	m/s	mile/h	ft/min	ft/s	in/s
1km/h	=	1	16.667	0.2778	0.6214	54.68	0.9113	10.936
m/min	=	0.06	1	16.7×10^{-3}	37.3×10^{-3}	3.281	54.7×10^{-3}	0.656
1m/s	=	3.6	60	1	2.237	196.85	3.281	39.37
1mile/h	=	1.609	26.82	0.4470	1	88	1.467	17.6
1ft/min	=	18.3×10^{-3}	0.3048	5.08×10^{-3}	11.4×10^{-3}	1	16.7×10^{-3}	0.2
1ft/s	=	1.097	18.288	0.3048	0.6818	60	1	12
1in/s	=	91×10^{-3}	1.524	25.4×10^{-3}	56.8×10^{-3}	5	83.3×10^{-3}	1

TORQUE

		Nm	Ncm	kgfm	lbf.ft	lbf.in	ozf.in
1Nm	=	1	100	0.10197	0.73756	8.8507	141.61
Ncm	=	0.01	1	1.02×10^{-3}	7.376×10^{-3}	88.5×10^{-3}	1.4161
1kgfm	=	9.8067	980.67	1	7.233	86.796	1389
1lbf.ft	=	1.356	135.6	0.1383	1	12	192
1lbf.in	=	0.1129	11.29	11.5×10^{-3}	83.3×10^{-3}	1	16
1ozf.in	=	7.062×10^{-3}	0.7062	0.72×10^{-3}	5.21×10^{-3}	62.5×10^{-3}	1

POWER

		kW	PS	hp	kgfm/s	ft.lbf/s
1kW	=	1	1.360	1.341	102.0	737.6
1PS	=	0.7355	1	0.9863	75	542.5
1hp	=	0.7457	1.014	1	76.04	550
1kgfm/s	=	9.81×10^{-3}	13.33×10^{-3}	13.15×10^{-3}	1	7.233
1ft.lbf/s	=	1.36×10^{-3}	1.84×10^{-3}	1.82×10^{-3}	0.1383	1

MOMENT OF INERTIA AND OTHER FLYWHEEL EFFECTS

		kgm ² (m ²)	kgfm ² (GD ²)	lb.ft ² (WK ²)	kpms ²	ft lbf s ²
1kgm ² (m ²)	=	1	4	23.73	0.102	0.7376
1kgfm ² (GD ²)	=	0.25	1	5.933	25×10^{-3}	0.1844
1lb.ft ² (WK ²)	=	42.1×10^{-3}	0.1686	1	4.30×10^{-3}	31.1×10^{-3}
1kpms ²	=	9.807	39.23	232.7	1	7.233
1ft lbf s ²	=	1.356	5.423	32.17	0.1383	1

LENGTH

	mm	m	in	ft	yds	km	miles
1mm	1	0.001	0.3937	0.0033	0.00109	-	-
1m	1000	1	39.370	3.2808	1.0936	0.001	0.0006215
1in	25.4	0.0254	1	0.0833	0.0277	0.0000254	0.0000158
1ft	304.8	0.3048	12	1	0.3333	0.000304	0.0001894
1yd	914.4	0.9144	36	3	1	0.000914	0.000568
1km	-	1000	39,370.07	3,280.83	1,093.613	1	0.6215
1mile	-	1,609	63,346.45	5,278.87	1,759.623	1.609	1

All Customer Service phone numbers shown in bold

Electromagnetic Clutches and Brakes

Warner Electric

Electromagnetic Clutches and Brakes

New Hartford, CT - USA
1-800-825-6544

For application assistance:
1-800-825-9050

St Barthelemy d'Anjou, France
+33 (0) 2 41 21 24 24

Precision Electric Coils and Electromagnetic Clutches and Brakes

Columbia City, IN - USA
1-260-244-6183

Matrix International

Electromagnetic Clutches and Brakes, Pressure Operated Clutches and Brakes

Brechin, Scotland
+44 (0) 1356 602000

New Hartford, CT - USA
1-800-825-6544

Inertia Dynamics

Spring Set Brakes; Power On and Wrap Spring Clutch/Brakes

New Hartford, CT - USA
1-800-800-6445

Linear Products

Warner Linear

Linear Actuators

Belvidere, IL - USA
1-800-825-6544

For application assistance:
1-800-825-9050

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+33 (0) 2 41 21 24 24

Couplings

Ameridrives Couplings

Mill Spindles, Ameriflex, Ameridisc

Erie, PA - USA
1-814-480-5000

Gear Couplings

San Marcos, TX - USA
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Bibby Turboflex

Disc, Gear, Grid Couplings, Overload Clutches

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+44 (0) 1924 460801

Boksburg, South Africa
+27 11 918 4270

TB Wood's

Elastomeric Couplings

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1-888-829-6637 – Press #5

For application assistance:
1-888-829-6637 – Press #7

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1-888-449-9439

Ameridrives Power Transmission

Universal Joints, Drive Shafts, Mill Gear Couplings

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Huco Dynatork

Precision Couplings and Air Motors

Hertford, England
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Lamiflex Couplings

Flexible Couplings, Bearing Isolators, and Coupling Guards

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(11) 5679-6533

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Wichita Clutch

Pneumatic Clutches and Brakes

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Caliper Brakes and Thrusters

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Gearing

Boston Gear

Enclosed and Open Gearing, Electrical and Mechanical P.T. Components

Charlotte, NC - USA
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For application assistance:
1-800-816-5608

Bauer Gear Motor

Geared Motors

Esslingen, Germany
+49 (711) 3518 0

Somerset, NJ - USA
1-732-469-8770

Nuttall Gear and Delroyd Worm Gear

Worm Gear and Helical Speed Reducers

Niagara Falls, NY - USA
1-716-298-4100

Overrunning Clutches

Formsprag Clutch

Overrunning Clutches and Holdbacks

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1-800-348-0881 – Press #1

For application assistance:
1-800-348-0881 – Press #2

Marland Clutch

Roller Ramp and Sprag Type Overrunning Clutches and Backstops

South Beloit, IL - USA
1-800-216-3515

Stieber Clutch

Overrunning Clutches and Holdbacks

Heidelberg, Germany
+49 (0) 6221 30 47 0

Belted Drives and Sheaves

TB Wood's

Belted Drives

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For application assistance:
1-888-829-6637 – Press #7

Engineered Bearing Assemblies

Kilian Manufacturing

Engineered Bearing Assemblies

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